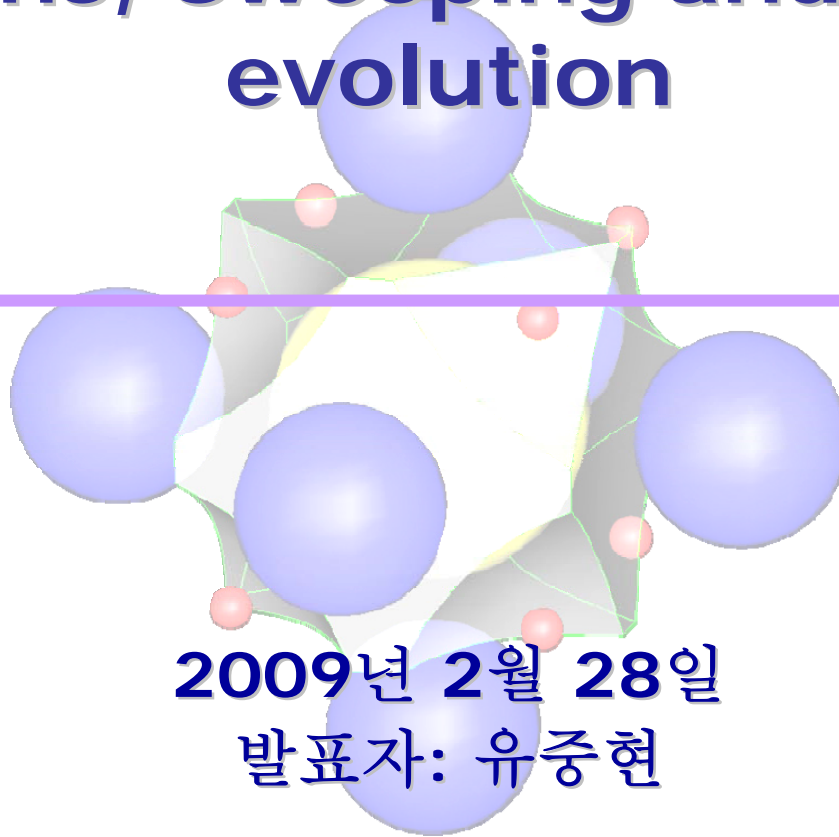
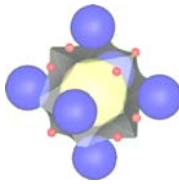


# Architectural geometry: Motions, Sweeping and Shape evolution

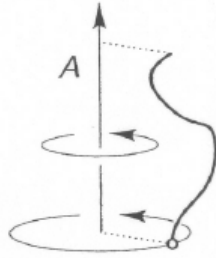
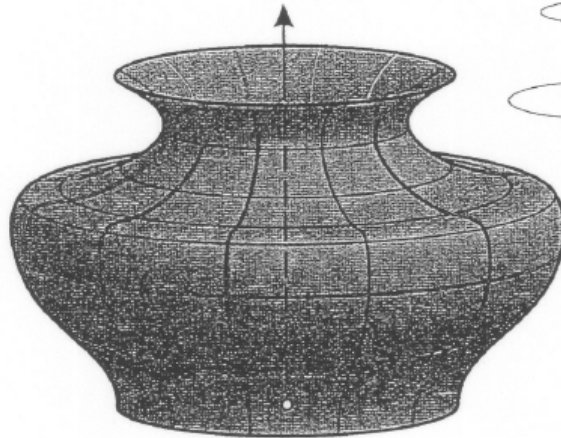


2009년 2월 28일  
발표자: 유중현

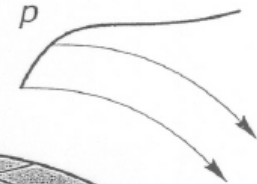
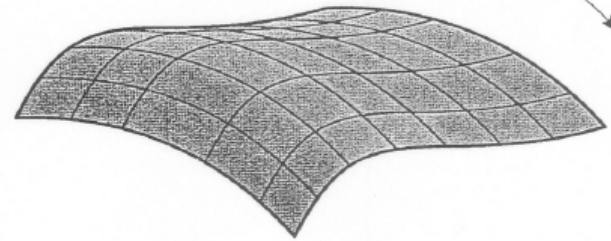


# Surfaces via motions

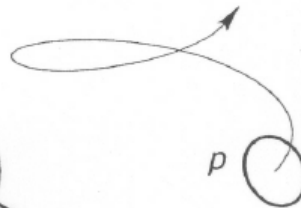
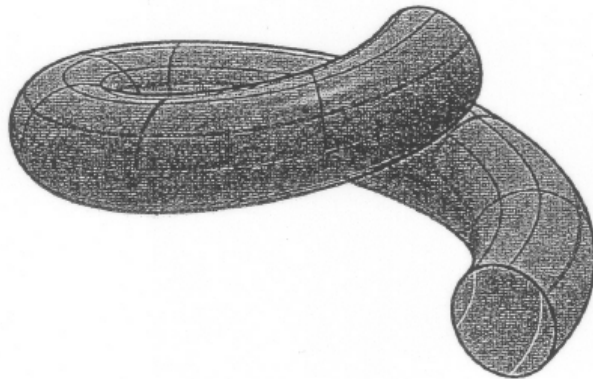
*rotational surface*



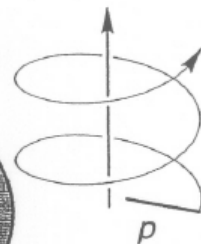
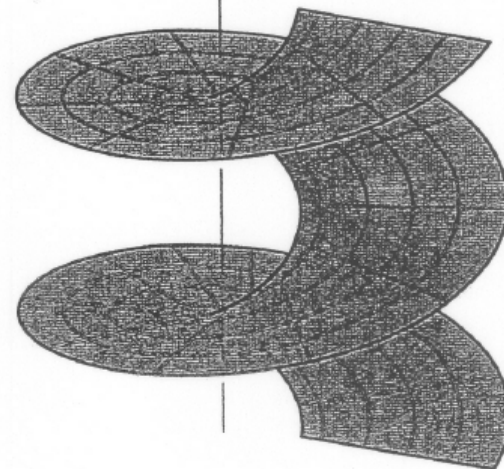
*translational surface*

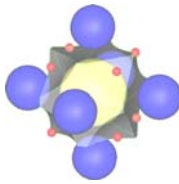


*pipe surface*



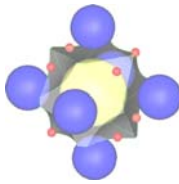
*helical surface*





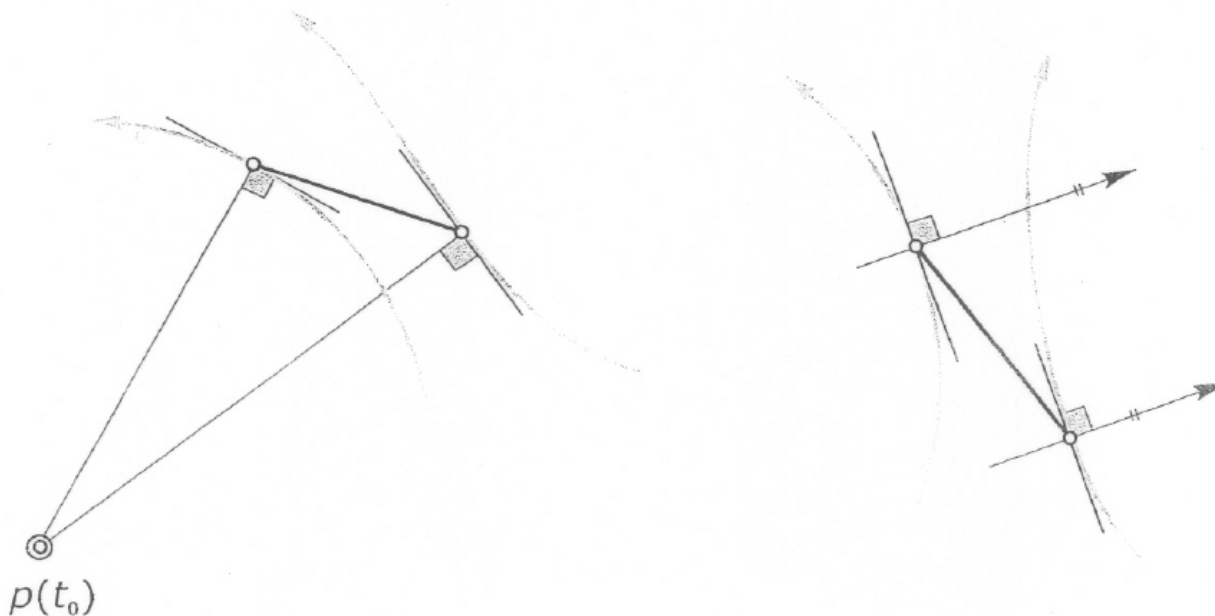
# Kinematic geometry

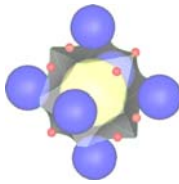
- (Geometry of motions)
- Basics for understanding of surface generation via motions
- Design and functionality can not be fully separated
  - Mechanical design
  - Architectural design
- Various surface classes are based on kinematic geometry
  - Surfaces via motion of profile curves
  - Surfaces via motion of profile curves which changes their shapes



# Motions in a plane

- Moving system  $M$  and fixed system  $F$  under a continuous motion
  - $M(t)$ : position of  $M$  in  $F$  at time  $t$
  - Path (or trajectory)
  - Path tangent/normal
  - Pole  $p(t)$  at time  $t$
  - Polehode: a set of poles in a system  $M$  or  $F$

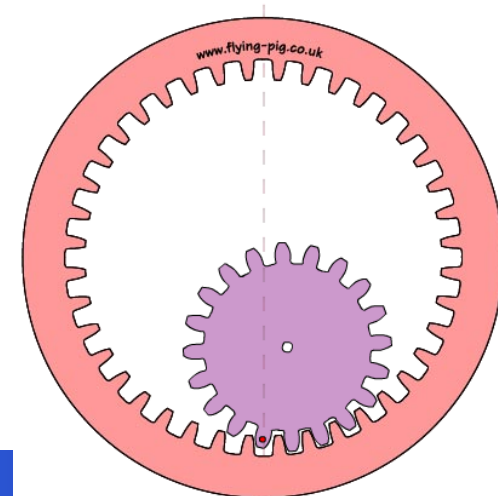
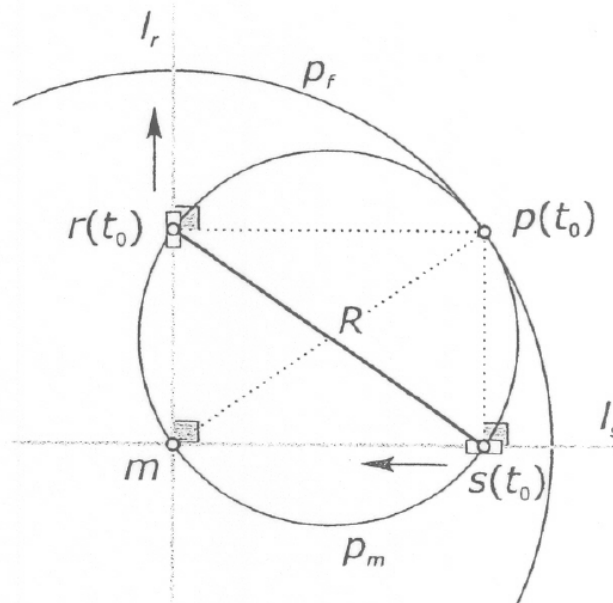
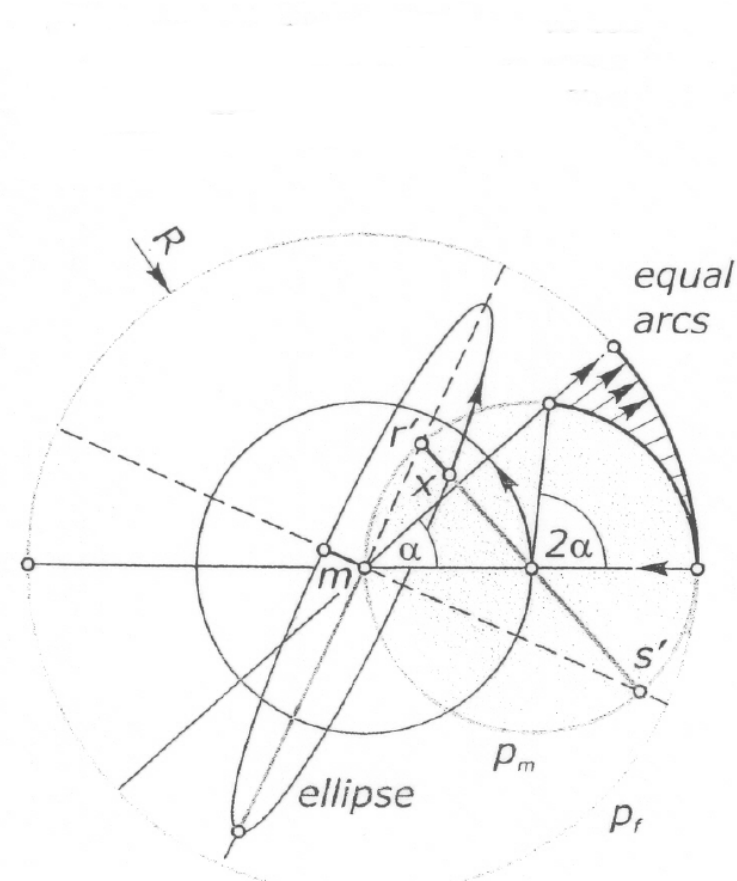


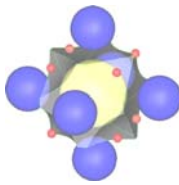


# Motions in a plane

## ■ Cardan motion

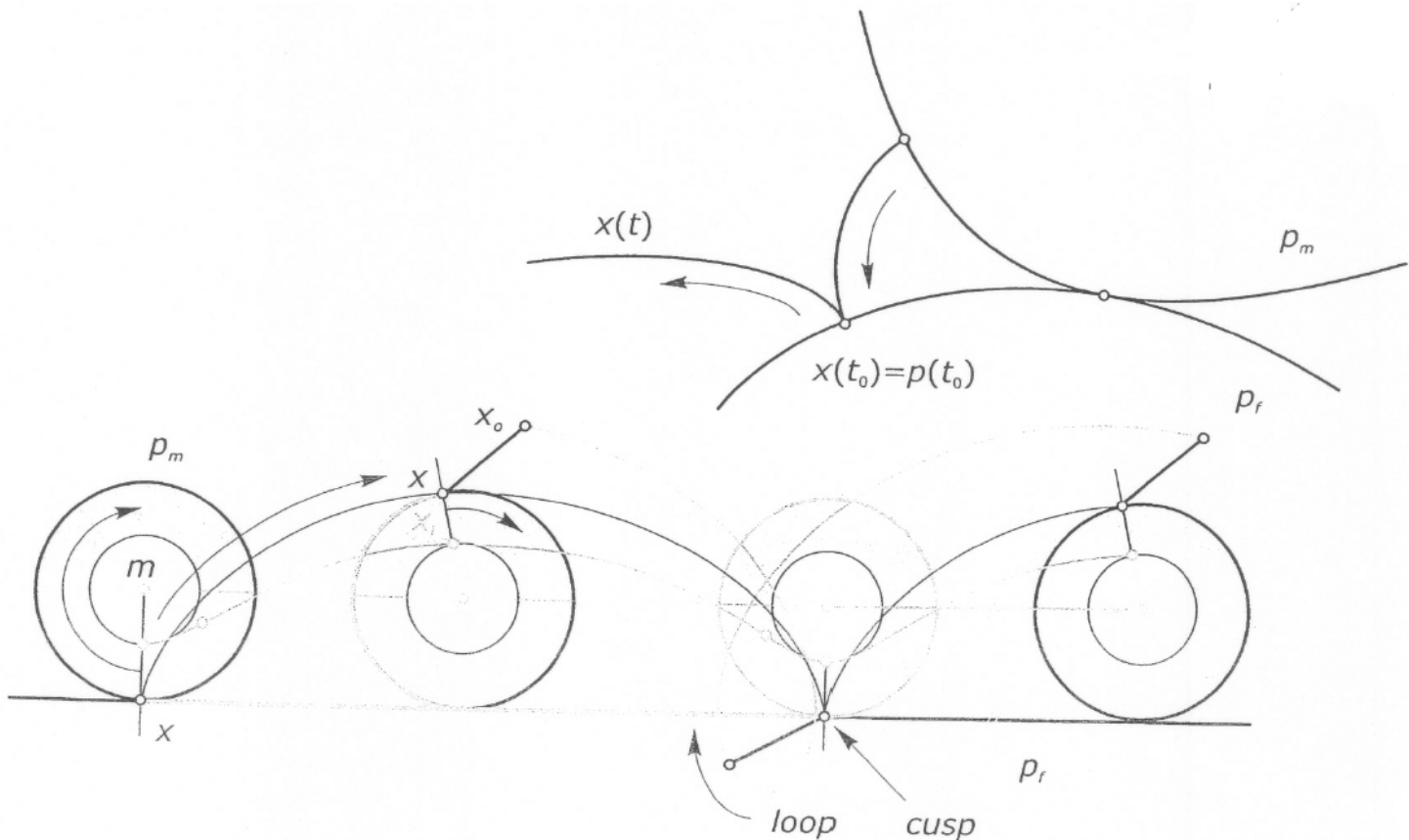
- Moving line segment with two points being in a constant speed
- The rolling motion of a circle  $p_m$  in a circle  $p_f$

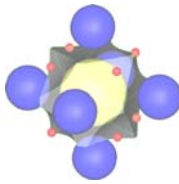




# Motions in a plane

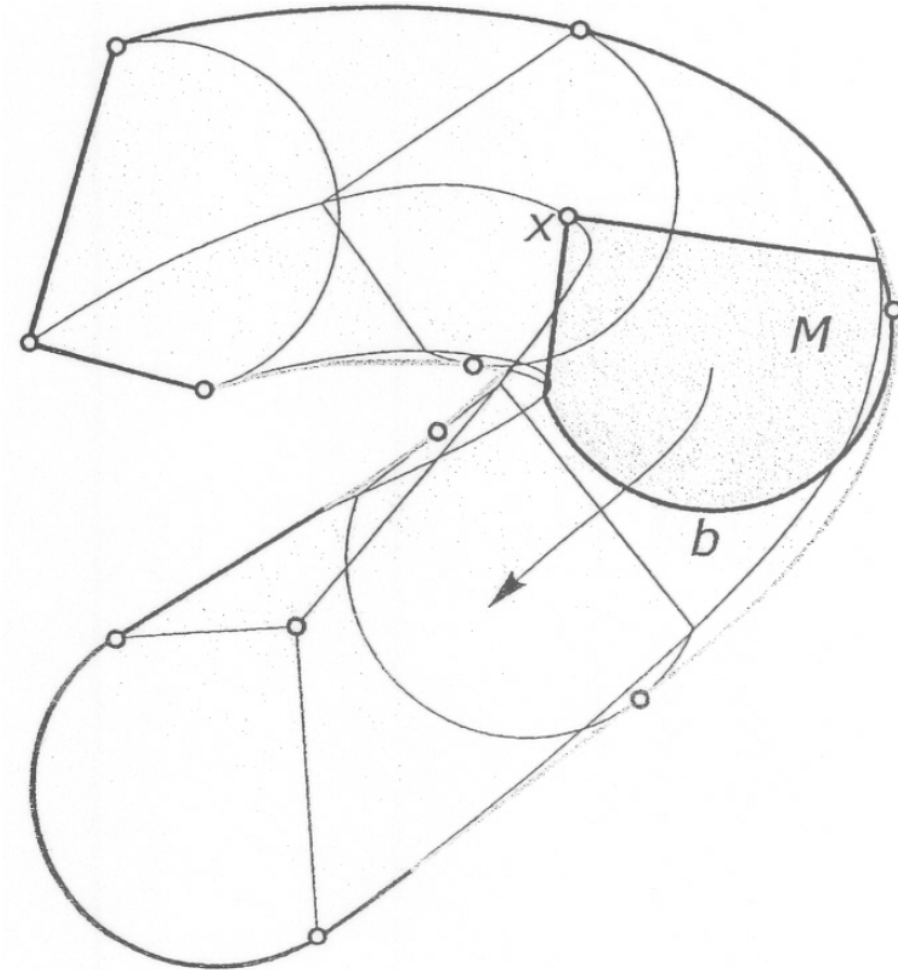
- The rolling motion of a circle  $p_m$  on a straight line  $p_f$ 
  - Cycloids
  - Cusps and loops



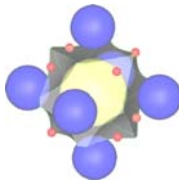


# Motions in a plane

- **Swept area** consists of two parts:
  - **Trajectory of a corner** of the object  $M$
  - **Envelopes of boundary curves** of  $M$
- **Application**
  - An interference free motion
  - Collision free path
    - Robotics

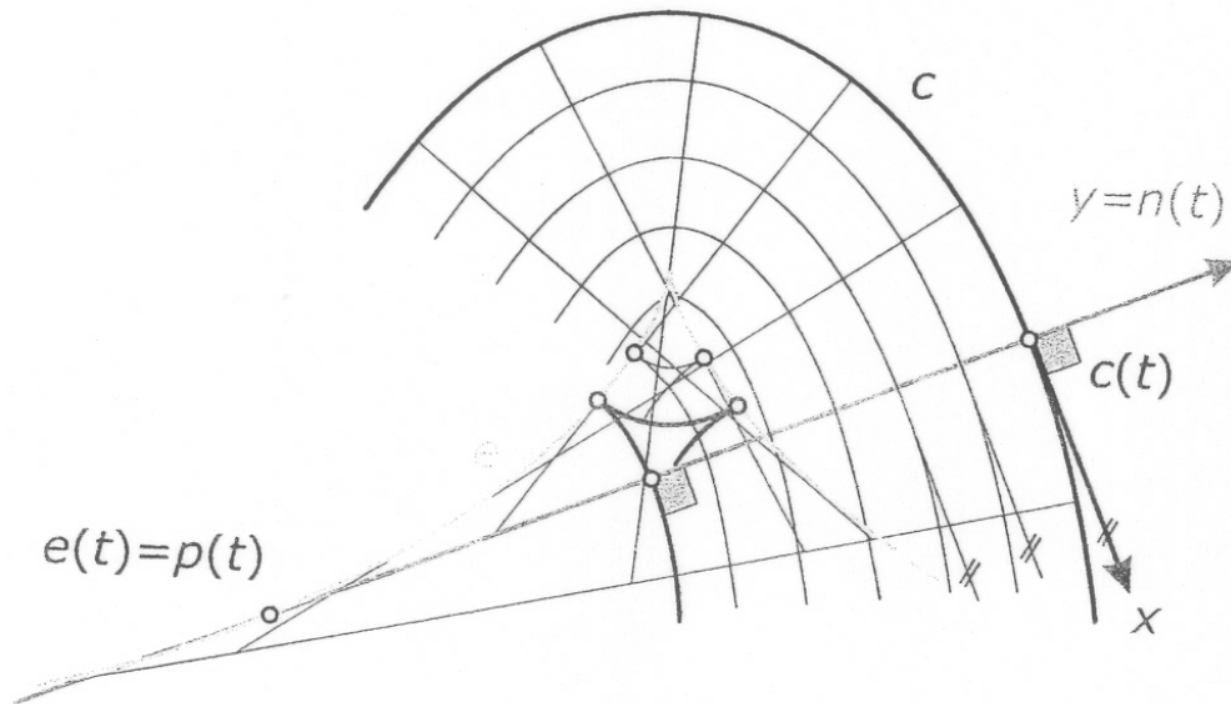






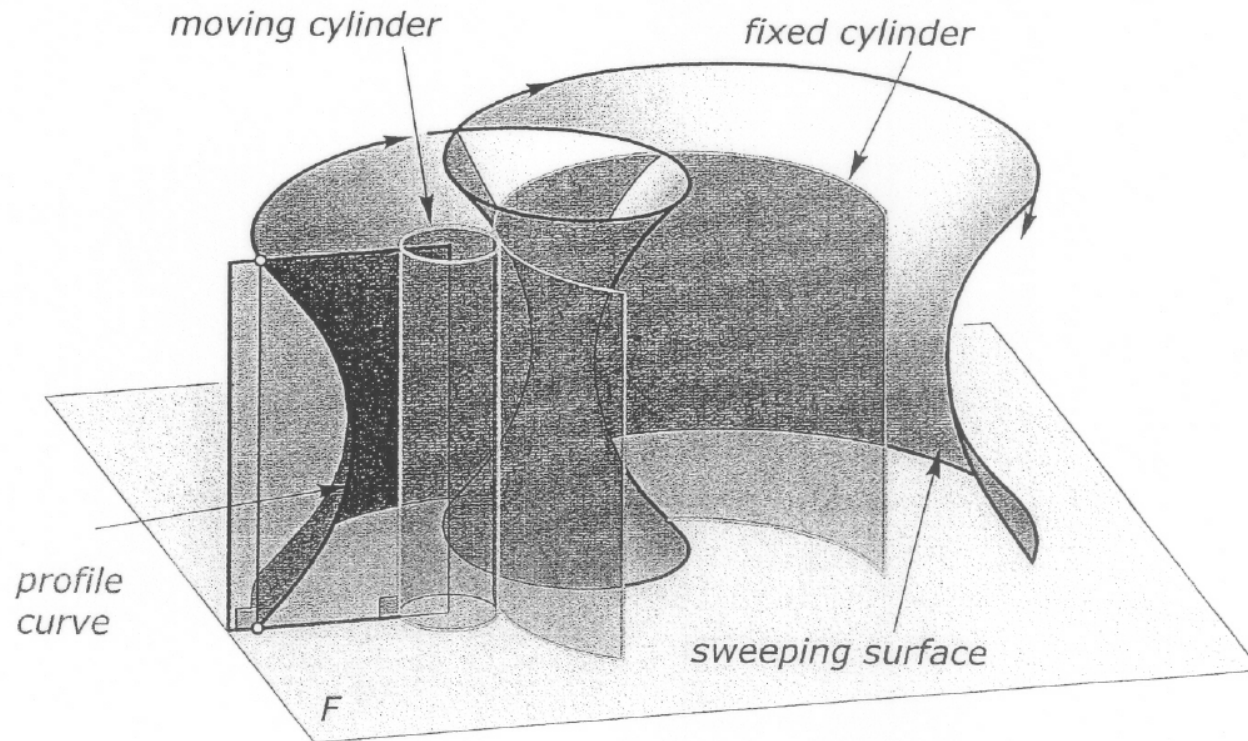
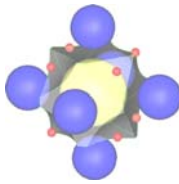
# Motions in a plane

- Motion of Frenet frame along a planar curve  $c$ 
  - Fixed polhode: evolute of  $c$
  - Moving polhode:  $y(t)$  (curve normal)

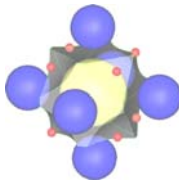




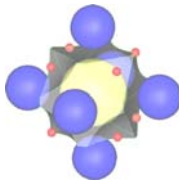
# Spatial motions



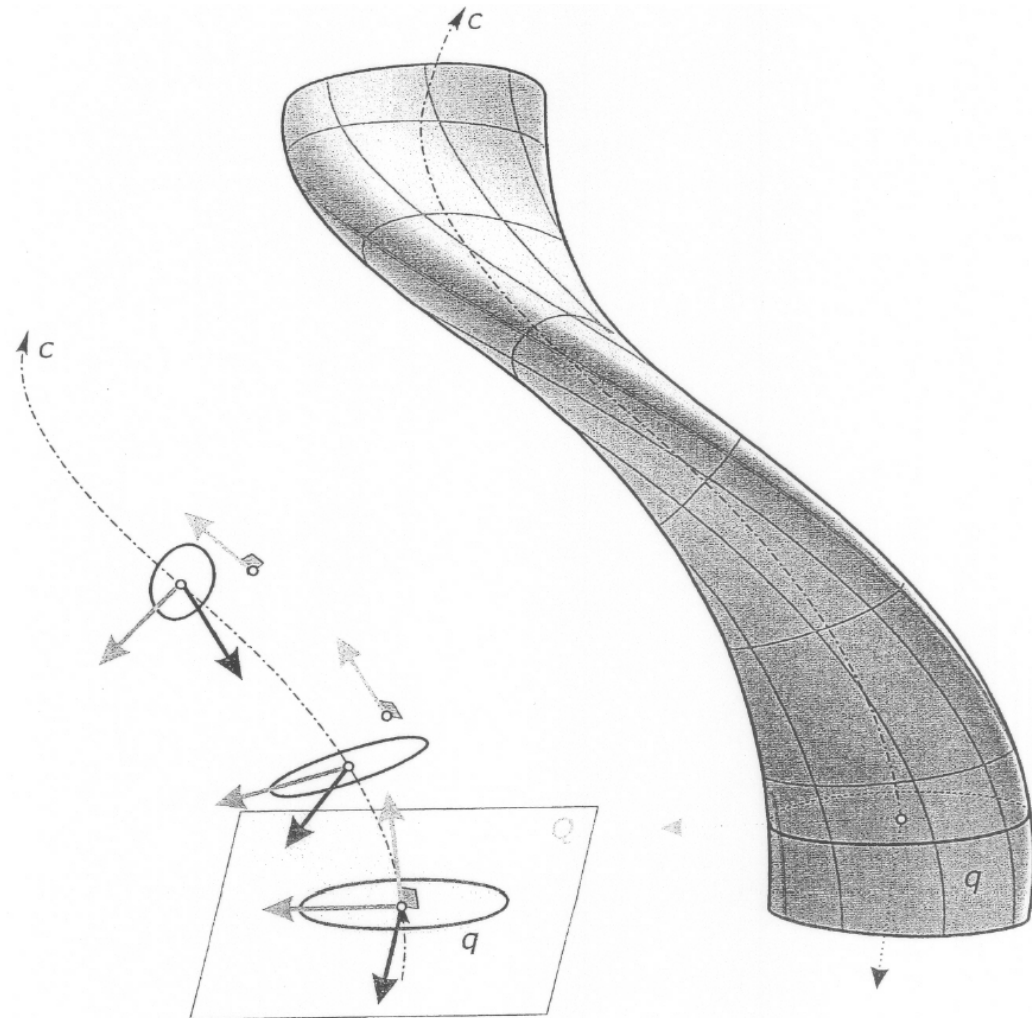
# Spatial motions



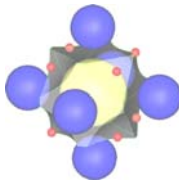
# Sweeping



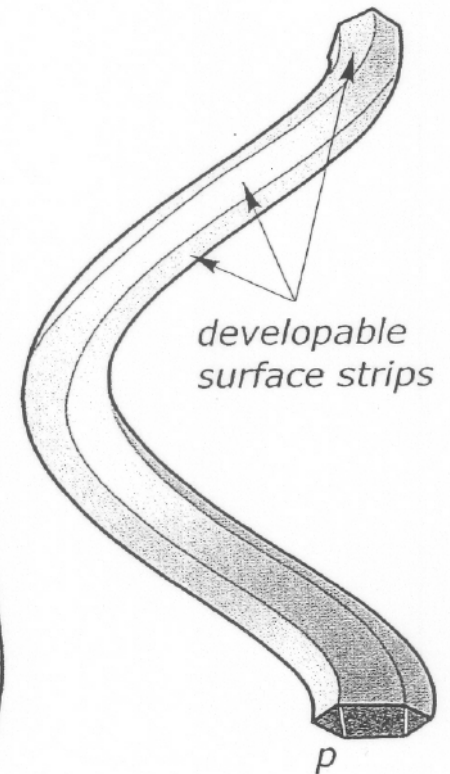
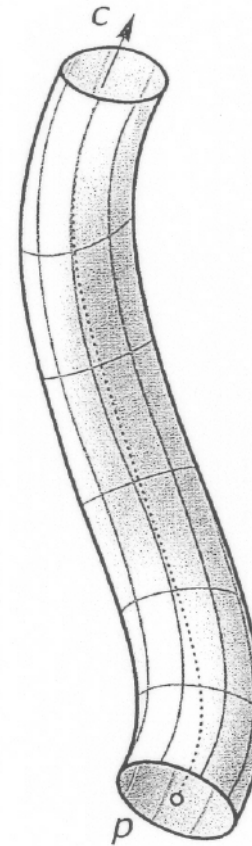
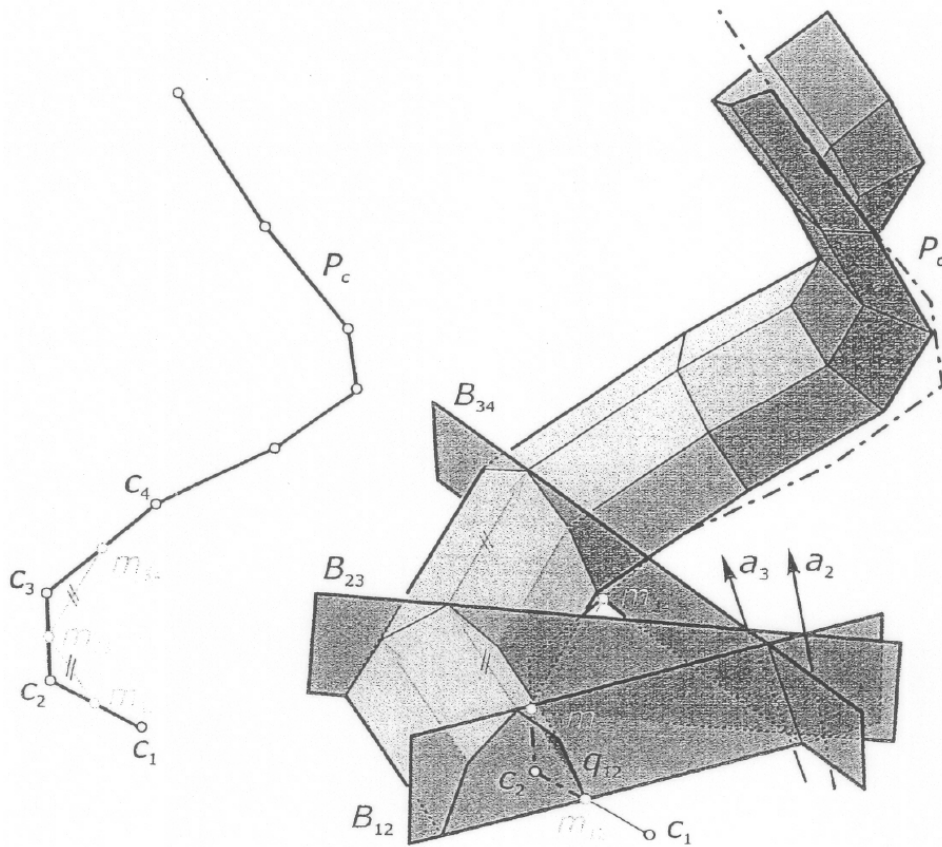
- Path  $c$ , source  $q$
- Degree of freedom: rotation about the tangent of  $c$



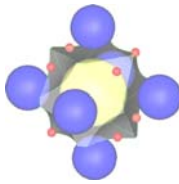
# Sweeping



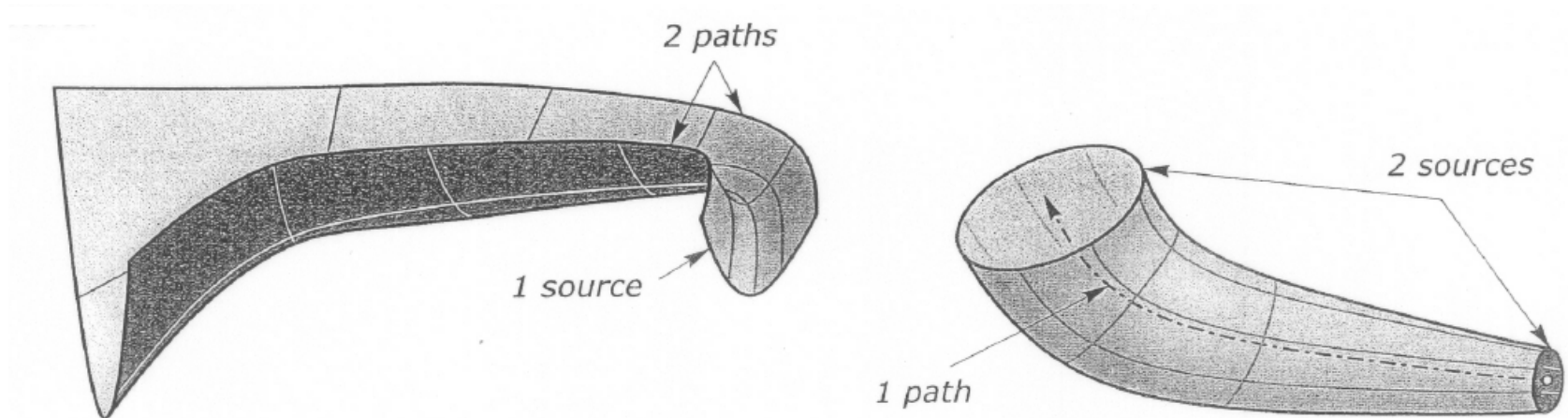
## ■ Rotation minimizing frame



# Sweeping

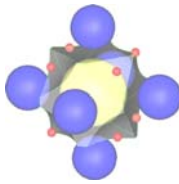


## ■ Sweeping with several sources and paths

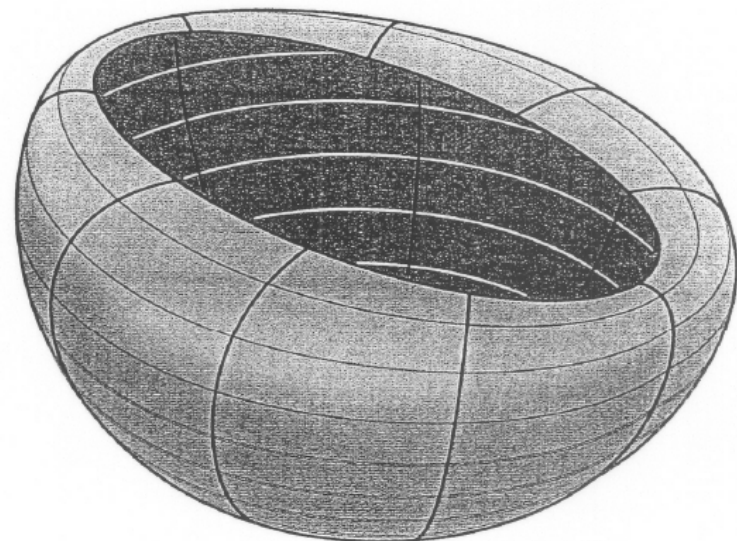
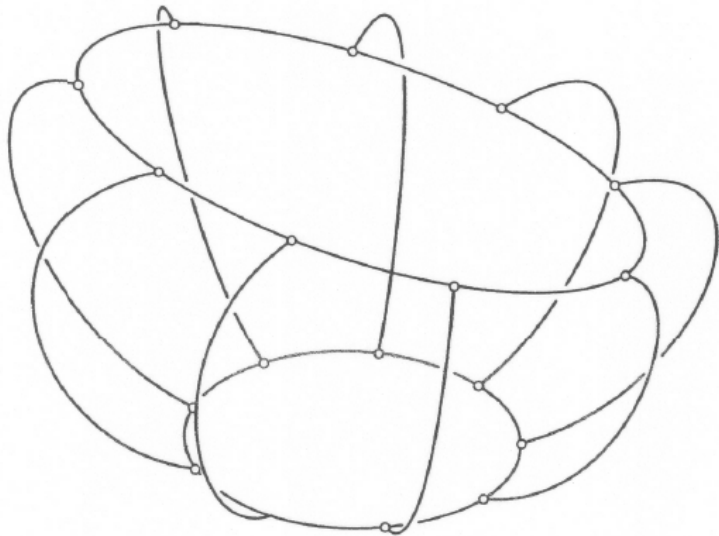




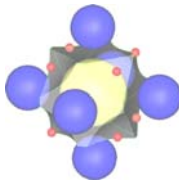
# Skinning



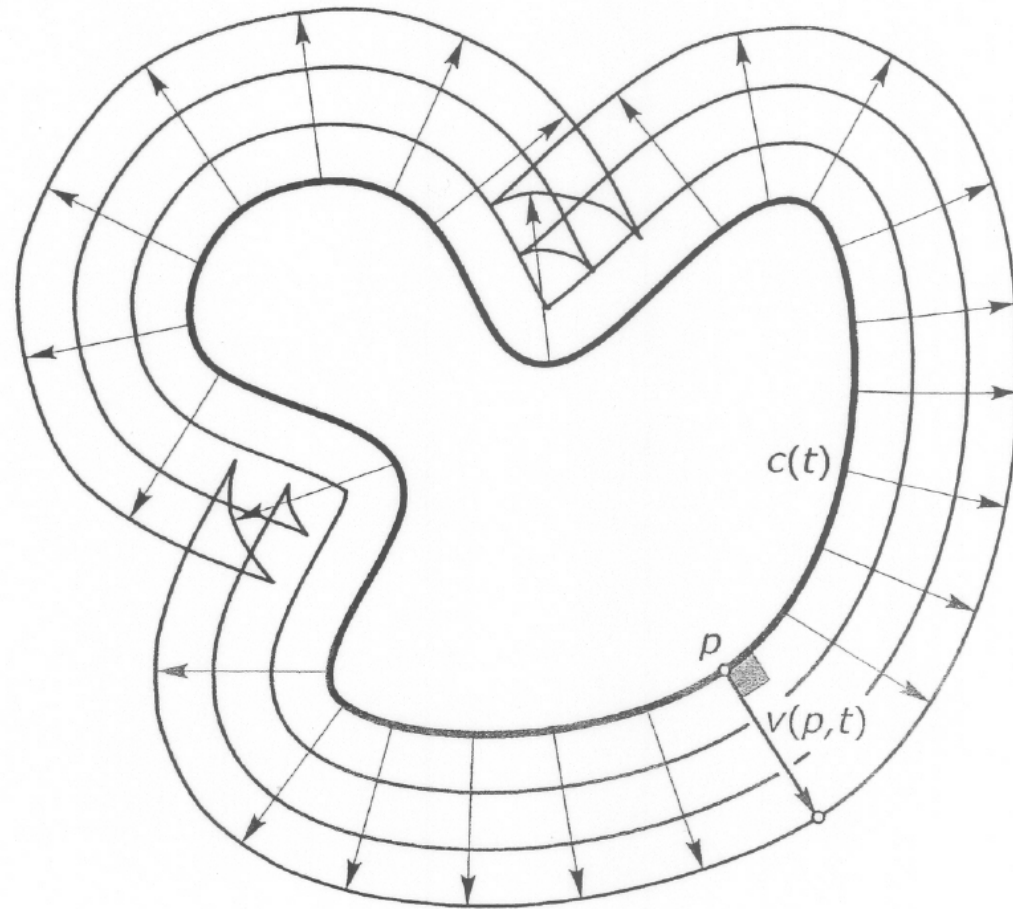
- Wrap a surface (skin) over a given network of curves
- A lot of degree of freedom
  - Depends on a specific modeling system and options (algorithm)



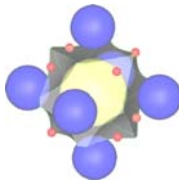
# Curve evolution



- The design of changing curves
  - Useful for modeling surfaces with a profile curve
- Evolutions of curves (curve flows)
- $v(p, t)$ : normal component of  $c(t)$

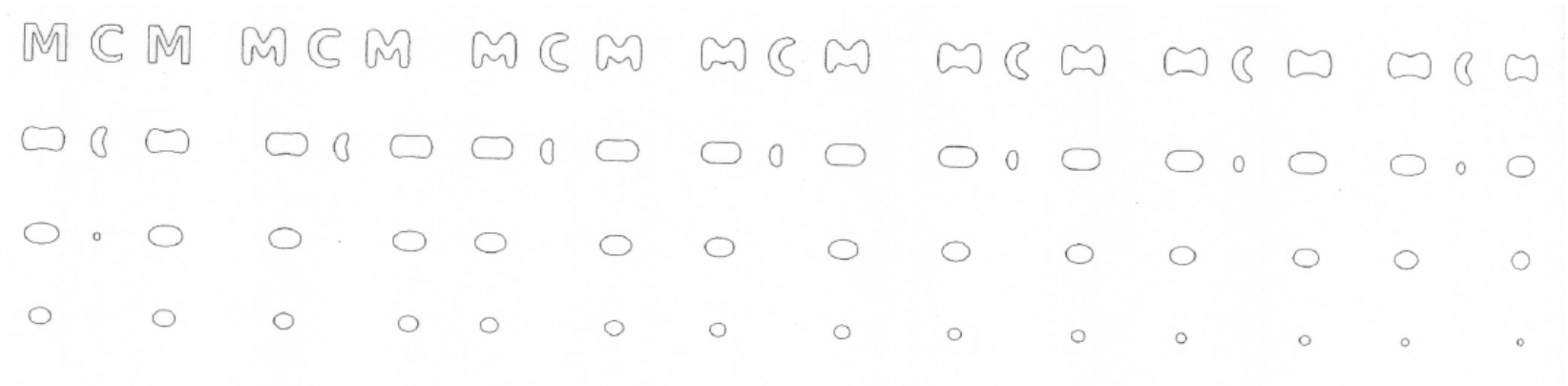


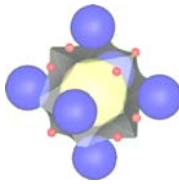




# Curve evolution

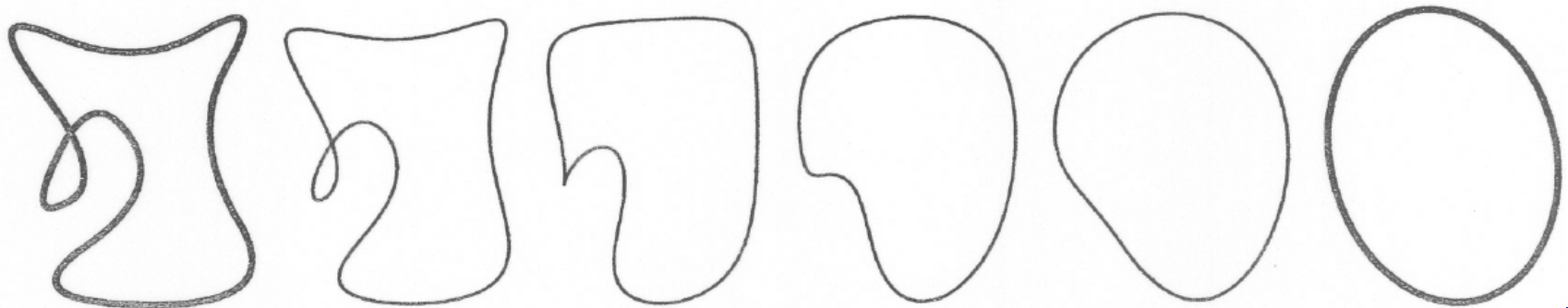
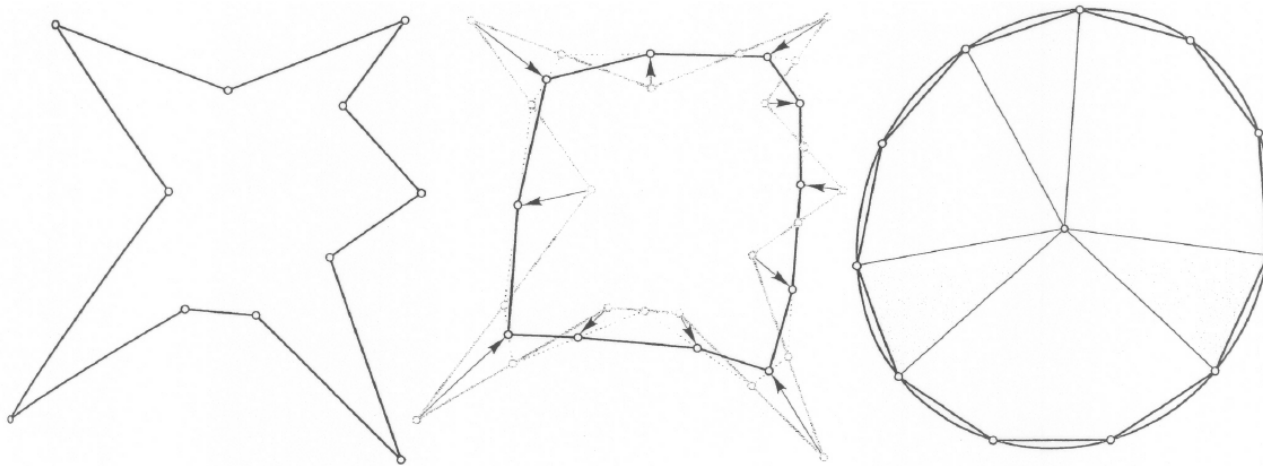
- **Curvature flow**
  - $\kappa(p, t)$ : curvature of  $c(t)$
- **Evolution of  $c(t)$  will shrink  $c(t)$  to a point**



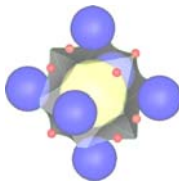


# Curve evolution

- Simple polygon evolution
  - Affinely regular polygon
  - Ellipse



# Metaballs and modeling with implicit surfaces

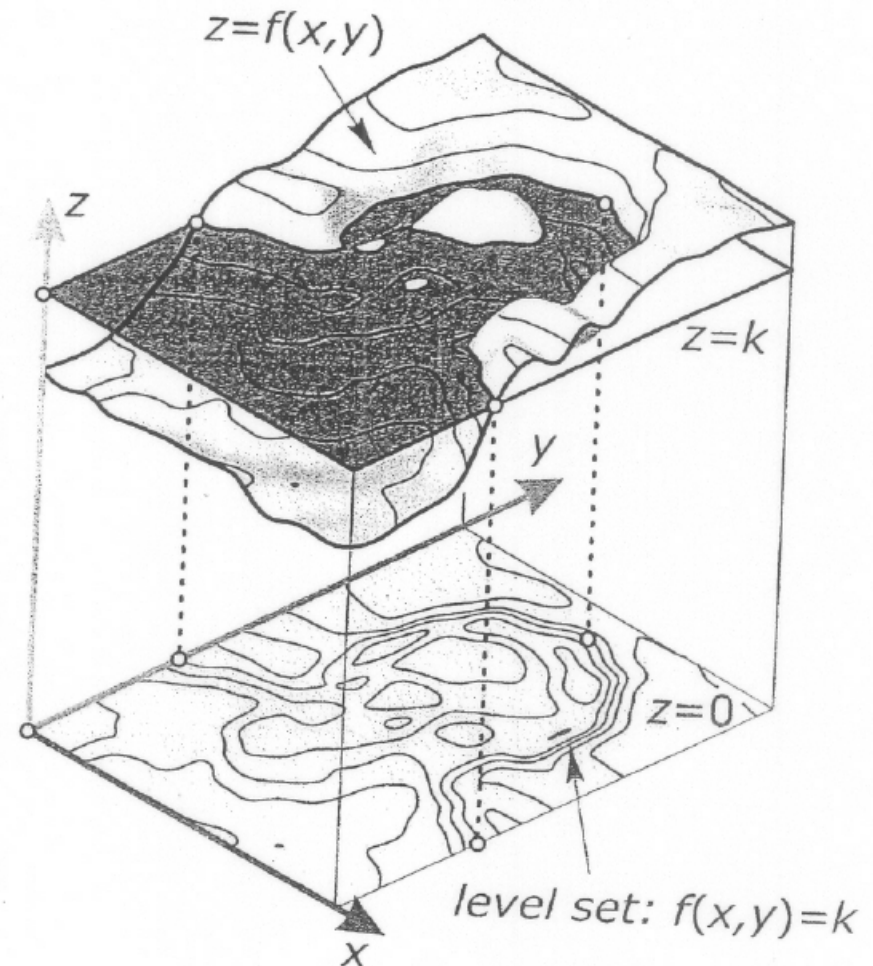


## ■ Implicit representation

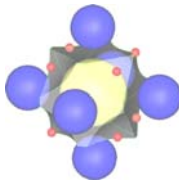
- Curve :  $f(x, y) = 0$
- Surface :  $f(x, y, z) = 0$

## ■ Level set

- $f(x, y) = k$
- $f(x, y, z) = k$



# Metaballs and modeling with implicit surfaces



- Distance-based functions (Df)

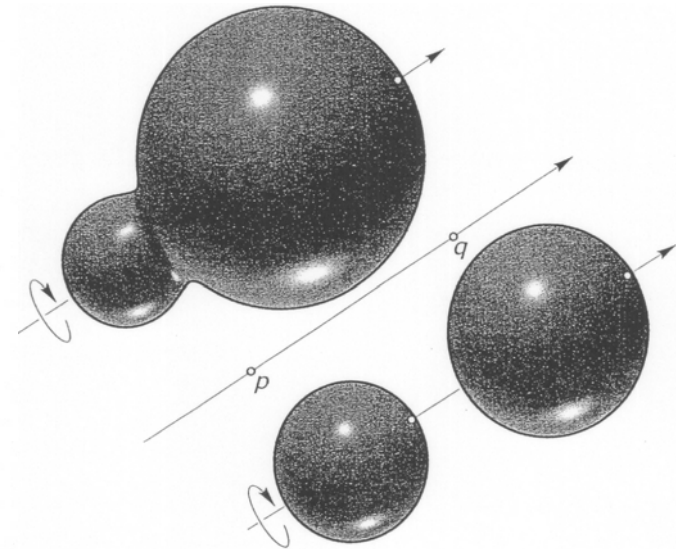
- Meta-balls

- Blobs or soft objects

$$f(x, y, z) = \sum_i Df_i(x, y, z), \quad f(x, y, z) = k$$

Gaussian model

modification



$$P(x, y, z) = a \cdot \exp(-b \cdot [(x - p_1)^2 + (y - p_2)^2 + (z - p_3)^2])$$