

Lec 5More About Matrices :-

Let A be a $n \times m$ matrix. There are two integers associated with A . One is called rank $= R(A)$ and the other is called nullity $= N(A)$. They are defined in such a way that

$$R(A) + N(A) = m$$

Fact : For any matrix A the # of l.i. rows equals the # of l.i. columns.

This number is called the rank of A .

Remark: By definition $R(A) \leq \min(m, n)$.

(5.2)

Example 5.1 :-

$$A = \begin{pmatrix} 3 & 6 & 9 \\ 4 & 8 & 12 \end{pmatrix}$$

$n=2, m=3.$

The vectors

$$\begin{pmatrix} 3 \\ 4 \end{pmatrix}, \begin{pmatrix} 6 \\ 8 \end{pmatrix}, \begin{pmatrix} 9 \\ 12 \end{pmatrix}$$

are l.d. There exists only one l.i. ^{column} vector

$$\begin{pmatrix} 3 \\ 4 \end{pmatrix}. \text{ Likewise } (3 \ 6 \ 9) \ \& \ (4 \ 8 \ 12)$$

are l.d.. There exists only one l.i. row

vector $(3 \ 6 \ 9)$. Hence

$$\text{rank } A = 1$$

(5.3)

Def: The row space of A is the vector space spanned by the rows of A .

The column space of A is the vector space spanned by the columns of A .

The null space of A is the set of all vectors x in \mathbb{R}^m such that $Ax=0$.

Fact :

$R(A)$ = dimension of the row space
= dimension of the column space.

$N(A)$ = dimension of the null space of A .

Example 5.1 (continued):

$$N(A) = m - R(A) = 3 - 1 = 2.$$

column space = $\begin{bmatrix} 3 \\ 4 \end{bmatrix}$

row space = $\begin{bmatrix} 3 \\ 6 \\ 9 \end{bmatrix}$

To find the null space:

$$x = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$Ax = 0$$

$$\Rightarrow \left. \begin{matrix} 3a + 6b + 9c = 0 \\ 4a + 8b + 12c = 0 \end{matrix} \right\} \Rightarrow a + 2b + 3c = 0$$

$$\Rightarrow a = -2b - 3c$$

$$x = \begin{pmatrix} -2b - 3c \\ b \\ c \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix} b + \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix} c$$

Null space = $\left[\begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix} \right]$

Determinant calculationExample 5.2 :

$$A = \begin{pmatrix} 3 & 6 & 9 \\ 1 & 2 & 5 \\ 0 & 1 & -3 \end{pmatrix} \leftarrow$$

det A is computed by expanding it with respect to any row or column.

Let us pick the 1st row.

$$\det A = 3 \begin{vmatrix} 2 & 5 \\ 1 & -3 \end{vmatrix} - 6 \begin{vmatrix} 1 & 5 \\ 0 & -3 \end{vmatrix} + 9 \begin{vmatrix} 1 & 2 \\ 0 & 1 \end{vmatrix}$$

$$= 3(-11) - 6(-3) + 9(1)$$

$$= -33 + 18 + 9 = -6$$

(5.6)

Let us pick the 2nd column.

$\det A =$

$$-6 \begin{vmatrix} 1 & 5 \\ 0 & -3 \end{vmatrix} + 2 \begin{vmatrix} 3 & 9 \\ 0 & -3 \end{vmatrix} - 1 \begin{vmatrix} 3 & 9 \\ 1 & 5 \end{vmatrix}$$

$$= -6(-3) + 2(-9) - 1(15-9)$$

$$= 18 - 18 - 6 = -6$$

Same as
before.

Try some other row or column

for practice.

Some simple facts about determinant

- ① Let A be any ^{square} $n \times n$ matrix. If B is another matrix obtained by interchanging any row or column of A , then
- $$\det A = -\det B.$$

Example 5.3:

$$A = \begin{pmatrix} 3 & 6 & 9 \\ 1 & 2 & 5 \\ 0 & 1 & -3 \end{pmatrix}$$

$$C = \begin{pmatrix} 1 & 2 & 5 \\ 3 & 6 & 9 \\ 0 & 1 & -3 \end{pmatrix}$$

$$B = \begin{pmatrix} 9 & 6 & 3 \\ 5 & 2 & 1 \\ -3 & 1 & 0 \end{pmatrix}$$

$$D = \begin{pmatrix} 1 & 2 & 5 \\ 0 & 1 & -3 \\ 3 & 6 & 9 \end{pmatrix}$$

We know from Example 5.2 that $\det A = -6$. Hence $\det B = 6$, $\det C = 6$
 $\det D = -6$

(5.8)

② Let A be any matrix such that a row or a column in A is repeated then

$$\det A = 0$$

Why? : Construct a matrix B out of

A by interchanging the row or column which is repeated. Clearly by assumption $B = A$. However we also have

$$\det A = -\det B$$

$$\text{Hence } \det A = -\det B = -\det A$$

$$\Rightarrow \det A = 0$$

Example 5.4

$$A = \begin{pmatrix} 3 & 6 & 3 \\ 1 & 2 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad \det A = 0$$

(5.9)

③ If any row or column of A is all zeros then $\det A = 0$.

Example 5.5

$$A = \begin{pmatrix} 0 & 6 & 3 \\ 0 & 2 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad \det A = 0$$

④ Let A and B be two square matrices that are equal except any one i^{th} row or column. Assume that this particular row or column in B is λ times the corresponding row or column in A respectively then

$$\det B = \lambda \det A$$

Example 5.6:

$$A = \begin{pmatrix} 3 & 6 & 3 \\ 1 & 2 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad B = \begin{pmatrix} 3 & 6 & 3 \\ 4 & 8 & 4 \\ 0 & 1 & 0 \end{pmatrix}$$

(5.10)

$$\det B = 4 \det A = 4(-6) = -24$$

(5) Let A be any square matrix.
Assume that B is constructed from
 A by adding the i^{th} row/column of A
to the j^{th} row/column of A respectively
where $i \neq j$, then

$$\det A = \det B$$

Example 5.7:

$$A = \begin{pmatrix} 3 & 6 & 3 \\ 1 & 2 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$B = \begin{pmatrix} 4 & 8 & 4 \\ 1 & 2 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$C = \begin{pmatrix} 3 & 6 & 9 \\ 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\det A = \det B = \det C$$

$$\text{det} \begin{pmatrix} a_{11} + b_{11} & a_{12} + b_{12} & \dots & a_{1n} + b_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix}$$

$$= \text{det} \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} +$$

$$\text{det} \begin{pmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix}$$

The same can be done in any other row or column.

Some not so simple facts about determinant :

① If $AB = C$

Where A, B, C are $n \times n$ matrices.

$$\det C = \det A \cdot \det B.$$

② If $C = A + B$

it is not true in general that

$$\det C \stackrel{??}{=} \det A + \det B.$$

③ If $B = A^{-1}$

Then

$$\det B = \frac{1}{\det A}.$$

A is invertible i.e. A^{-1} exists iff.

$$\det A \neq 0.$$

5.13

④ If $B = A^T$

A is a $n \times n$ matrix then

$$\det B = \det A.$$

Def: A $n \times n$ matrix A is said to be invertible if \exists another $n \times n$ matrix B such that $BA = AB = I$.

Such a matrix B is denoted by A^{-1} .

Note that $\det I = 1$. Hence

$$\det(AB) = \det A \cdot \det B = 1$$

$$\Rightarrow \det A = \frac{1}{\det B}$$

Fact: If A is invertible then

$$A^{-1} = \frac{1}{\det A} \text{adj } A$$

Since $\det A \neq 0$, $\frac{1}{\det A}$ exists.

5.14

Less intuitive fact about determinant:

① Let $H = \begin{pmatrix} A & B \\ C & D \end{pmatrix}^{n \times n}$

A is $m \times m$ $m+p=n$
 D is $p \times p$

H is $n \times n$

A is $m \times m$ $m+p=n$

D is $p \times p$

If A is invertible then we can write

$$\det H = \det A \det (D - CA^{-1}B)$$

Example 5.8:

$$H = \begin{pmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & 8 & 5 \\ 3 & 2 & 6 & 5 \\ 5 & 6 & 0 & 0 \end{pmatrix}$$

5.15

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad A^{-1} = A \quad \det A = 1$$

$$\det H = \det(D - CB)$$

$$D = \begin{pmatrix} 6 & 5 \\ 0 & 0 \end{pmatrix}, \quad C = \begin{pmatrix} 3 & 2 \\ 5 & 6 \end{pmatrix}, \quad B = \begin{pmatrix} 2 & 1 \\ 8 & 5 \end{pmatrix}$$

$$CB = \begin{pmatrix} 6+16 & 3+10 \\ 10+48 & 5+30 \end{pmatrix} = \begin{pmatrix} 22 & 13 \\ 58 & 35 \end{pmatrix}$$

$$D - CB = \begin{pmatrix} -16 & -8 \\ -58 & -35 \end{pmatrix}$$

$$\det H = 16 \cdot 35 - 58 \cdot 8$$

$$= 560 - 464$$

$$= 96$$

② Let

$$H = \begin{pmatrix} A & B \\ C & D \end{pmatrix}$$

$n \times n$ $m \times m$ $p \times p$

If D is invertible then

$$\det H = \det D \det (A - BD^{-1}C)$$

If A and D are both singular
that is they cannot be inverted
bad luck.

(5.17)

③ Let A be a $m \times n$ matrix $n > m$.
Let B be a $n \times m$ matrix

Define $C = AB$ so that C is a
 $m \times m$ matrix. Then

$$\det C = \sum_{i_1, \dots, i_m=1}^n \det A_{i_1, \dots, i_m} \cdot \det B_{i_1, \dots, i_m}$$

where A_{i_1, \dots, i_m} is a $m \times m$ square
matrix obtained by stacking i_j^{th} column
of A as the j^{th} column for $j=1, 2, \dots, m$.

Example 5.9:

$$A = \begin{pmatrix} 3 & 5 & 1 \\ 2 & 6 & 9 \end{pmatrix}, \quad B = \begin{pmatrix} 3 & 6 \\ 5 & -1 \\ 2 & 4 \end{pmatrix}$$

$$C = AB$$

5-18

$$\det C =$$

$$\begin{vmatrix} 3 & 5 \\ 2 & 6 \end{vmatrix} + \begin{vmatrix} 3 & 6 \\ 5 & -1 \end{vmatrix} + \begin{vmatrix} 3 & 1 \\ 2 & 9 \end{vmatrix} + \begin{vmatrix} 3 & 6 \\ 2 & 4 \end{vmatrix} \\ + \begin{vmatrix} 5 & 1 \\ 6 & 9 \end{vmatrix} + \begin{vmatrix} 5 & -1 \\ 2 & 4 \end{vmatrix}$$

Example 5.10

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 4 & 3 & 1 \end{pmatrix}$$

$$\begin{aligned} \det A &= \det \begin{pmatrix} 0 & 1 \\ 3 & 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 4 \end{pmatrix} \det \begin{pmatrix} 1 & 0 \end{pmatrix} \\ &= \det \left(\begin{pmatrix} 0 & 1 \\ 3 & 1 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 4 & 0 \end{pmatrix} \right) \\ &= \det \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix} = -1 + 1 = 0 \end{aligned}$$

Fact: If a matrix A is of rank r , determinant of all $p \times p$ minors of A are zero for $p > r$. Furthermore \exists at least one $r \times r$ minor of non-zero determinant.

Example 5.11

$$A = \begin{pmatrix} 5 & 10 & 15 \\ 6 & 12 & 18 \\ 9 & 18 & 27 \end{pmatrix}$$

$$\text{rank } A = 1$$

$$A_{12} = \begin{pmatrix} 5 & 10 \\ 6 & 12 \end{pmatrix}$$

$$A_{13} = \begin{pmatrix} 5 & 15 \\ 9 & 27 \end{pmatrix}$$

$$A_{23} = \begin{pmatrix} 12 & 18 \\ 18 & 27 \end{pmatrix}$$

These are 2×2
principal minors

5-20

$$\begin{pmatrix} 10 & 15 \\ 18 & 27 \end{pmatrix}, \begin{pmatrix} 6 & 18 \\ 9 & 27 \end{pmatrix} \text{ etc are}$$

non-principal minors of A

check that the determinant of all these minors are zero.

— X —

Rank 1 matrix :

Let A be a $n \times n$ rank 1 matrix. It can always be written as a product of a column vector and a row vector.

ie

$$A = b c^T$$

where

$$b = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \quad c = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}$$

(5.21)

Example 5.11 (continued)

$$A = \begin{pmatrix} 5 \\ 6 \\ 9 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \end{pmatrix}$$

\uparrow
 b

\uparrow
 c^T

Of course the choice of b and c are not unique

— x —

Fact: Let $A = bc^T$ be any rank 1 matrix then

$$\text{trace } A = c^T b$$

In fact if M is any $n \times n$ matrix then

$$\boxed{\text{trace } M(bc^T) = c^T M b}$$

The story of $\det(\lambda I + A)$:-

For every square $n \times n$ matrix A
 \exists a polynomial of degree n given
by

$$\det(\lambda I + A) =$$

$$\lambda^n + \Delta_1 \lambda^{n-1} + \Delta_2 \lambda^{n-2} + \dots + \Delta_n.$$

What is perhaps surprising is that

$\Delta_j =$ sum of determinants of all
 $j \times j$ principal minors of A .

In particular

$$\Delta_1 = \text{trace } A$$

$$\Delta_n = \det A.$$

5.23

Example 5.12

consider matrix A in Example 5.2.

$$\lambda I + A = \begin{pmatrix} \lambda + 3 & 6 & 9 \\ 1 & \lambda + 2 & 5 \\ 0 & 1 & \lambda - 3 \end{pmatrix}$$

$$\det(\lambda I + A) =$$

$$(\lambda + 3) \det \begin{pmatrix} \lambda + 2 & 5 \\ 1 & \lambda - 3 \end{pmatrix}$$

$$-1 \det \begin{pmatrix} 6 & 9 \\ 1 & \lambda - 3 \end{pmatrix}$$

$$= (\lambda + 3) [\lambda^2 + 2\lambda - 3\lambda - 6 - 5] - [6\lambda - 18 - 9]$$

$$= (\lambda + 3)(\lambda^2 - \lambda - 11) - (6\lambda - 27)$$

$$= \lambda^3 - \lambda^2 - 11\lambda + 3\lambda^2 - 3\lambda - 33 - 6\lambda + 27$$

$$= \lambda^3 + 2\lambda^2 - 20\lambda - 6$$

\uparrow trace A \uparrow det A

What is -20??

It is $\begin{vmatrix} 3 & 6 \\ 1 & 2 \end{vmatrix} + \begin{vmatrix} 3 & 9 \\ 0 & -3 \end{vmatrix} + \begin{vmatrix} 2 & 5 \\ 1 & -3 \end{vmatrix}$

$$= 0 + (-9) + (-6 - 5)$$

$$= -20$$

Sum of all 2x2 principal minors of A.

(5.25)

Special case:

If we substitute $\lambda = 1$ in the identity

$$\det(\lambda I + A) = \lambda^n + \Delta_1 \lambda^{n-1} + \dots + \Delta_n$$

we obtain

$$\det(I + A) = 1 + \Delta_1 + \dots + \Delta_n.$$

If A is a rank 1 $n \times n$ matrix it follows that

$$\det(I + A) = 1 + \text{trace } A$$

↑
 A is rank 1.

Writing $A = bc^T$ we have

$$\det(I + bc^T) = 1 + c^T b.$$

Example 5.13

If B is an invertible matrix and if A is a rank 1 matrix we can write $A = bc^T$. It follows that

$$B + A = B(I + B^{-1}bc^T)$$

$$\det(B + A) = \det B (1 + c^T B^{-1}b)$$

Actually

$$\det(B + A) = \det B \det(I + B^{-1}bc^T)$$

$$= \det B (1 + \text{trace } \underbrace{B^{-1}bc^T}_{\substack{\uparrow \\ \text{rank 1 matrix.}}})$$

$$= \det B (1 + c^T B^{-1}b)$$

Since $B^{-1} = \text{adj } B / \det B$, we have

$$\boxed{\det(B + A) = \det B + c \text{ adj } B b}$$

↑
Rank 1 perturbation of the B matrix.

$\det(\lambda I + A)$ is close but not exactly the characteristic polynomial of A .

The characteristic polynomial $p(\lambda)$ is

$$p(\lambda) = \det(\lambda I - A)$$

$$= \lambda^n - \Delta_1 \lambda^{n-1} + \Delta_2 \lambda^{n-2} - \Delta_3 \lambda^{n-3} + \dots \\ \dots + (-1)^n \Delta_n.$$

Example 5.14 :

$$A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\delta_3 & -\delta_2 & -\delta_1 \end{pmatrix}$$

In the notation of page 5.22 we have

$$\Delta_1 = -\delta_1$$

$$\Delta_2 = \delta_2$$

$$\Delta_3 = -\delta_3$$

Hence

$$\det(\lambda I - A) =$$

$$\lambda^3 + \delta_1 \lambda^2 + \delta_2 \lambda + \delta_3$$

Similarity Transformation

Let A be any $n \times n$ matrix

Let T be any $n \times n$ invertible matrix
i.e. T^{-1} exists. We define

$B = T^{-1}AT$ called the similarity transformation of A .

Def: The matrices A and B are called similar if $\exists T : B = T^{-1}AT$.

Fact: The characteristic polynomials of two similar matrices are the same.

Let $p_1(\lambda) = \det(\lambda I - A)$ & $B = T^{-1}AT$
 $p_2(\lambda) = \det(\lambda I - B)$

we have

$$\begin{aligned} p_2(\lambda) &= \det(\lambda I - T^{-1}AT) \\ &= \det(T^{-1}(\lambda I - A)T) \end{aligned}$$

5.29

$$\begin{aligned} &= \det(T^{-1}) \det(\lambda I - A) \det T \\ &= \frac{1}{\det T} p_1(\lambda) \det T = p_1(\lambda). \end{aligned}$$

Corollary:

$\Delta_1, \Delta_2, \dots, \Delta_n$ are all invariant

under similarity transformations. In

particular if

$$B = T^{-1} A T$$

then

$$\det B = \det A$$

$$\text{trace } B = \text{trace } A.$$

etc.